## The dihedral groups

The general setup. The dihedral group  $D_n$  is the group of symmetries of a regular polygon with n vertices. We think of this polygon as having vertices on the unit circle, with vertices labeled  $0, 1, \ldots, n-1$  starting at (1,0) and proceeding counterclockwise at angles in multiples of 360/n degrees, that is,  $2\pi/n$  radians.

There are two types of symmetries of the n-gon, each one giving rise to n elements in the group  $D_n$ :

- Rotations  $R_0, R_1, \ldots, R_{n-1}$ , where  $R_k$  is rotation of angle  $2\pi k/n$ .
- Reflections  $S_0, S_1, \ldots, S_{n-1}$ , where  $S_k$  is reflection about the line through the origin and making an angle of  $\pi k/n$  with the horizontal axis.

The group operation is given by composition of symmetries: if a and b are two elements in  $D_n$ , then  $a \cdot b = b \circ a$ . That is to say,  $a \cdot b$  is the symmetry obtained by applying first a, followed by b.

The elements of  $D_n$  can be thought as linear transformations of the plane, leaving the given n-gon invariant. This lets us represent the elements of  $D_n$  as  $2 \times 2$  matrices, with group operation corresponding to matrix multiplication. Specifically,

$$R_k = \begin{pmatrix} \cos(2\pi k/n) & -\sin(2\pi k/n) \\ \sin(2\pi k/n) & \cos(2\pi k/n) \end{pmatrix},$$

$$S_k = \begin{pmatrix} \cos(2\pi k/n) & \sin(2\pi k/n) \\ \sin(2\pi k/n) & -\cos(2\pi k/n) \end{pmatrix}.$$

It is now a simple matter to verify that the following relations hold in  $D_n$ :

$$R_{i} \cdot R_{j} = R_{i+j}$$

$$R_{i} \cdot S_{j} = S_{i+j}$$

$$S_{i} \cdot R_{j} = S_{i-j}$$

$$S_{i} \cdot S_{j} = R_{i-j}$$

where  $0 \le i, j \le n-1$ , and both i+j and i-j are computed modulo n.

The Cayley table for  $D_n$  can be readily computed from the above relations. In particular, we see that  $R_0$  is the identity,  $R_i^{-1} = R_{n-i}$ , and  $S_i^{-1} = S_i$ .

The group  $D_3$ . This is the symmetry group of the equilateral triangle, with vertices on the unit circle, at angles 0,  $2\pi/3$ , and  $4\pi/3$ . The matrix representation is given by

$$R_{0} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \qquad R_{1} = \begin{pmatrix} -\frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix}, \qquad R_{2} = \begin{pmatrix} -\frac{1}{2} & \frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix},$$

$$S_{0} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \qquad S_{1} = \begin{pmatrix} -\frac{1}{2} & \frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & \frac{1}{2} \end{pmatrix}, \qquad S_{2} = \begin{pmatrix} -\frac{1}{2} & -\frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & \frac{1}{2} \end{pmatrix}.$$

while the Cayley table for  $D_3$  is:

	$R_0$	$R_1$	$R_2$	$S_0$	$S_1$	$S_2$
$R_0$	$R_0$	$R_1$	$R_2$	$S_0$	$S_1$	$S_2$
$R_1$	$R_1$	$R_2$	$R_0$	$S_1$	$S_2$	$S_0$
$R_2$	$R_2$	$R_0$	$R_1$	$S_2$	$S_0$	$S_1$
$S_0$	$S_0$	$S_2$	$S_1$	$R_0$	$R_2$	$R_1$
$S_1$	$S_1$	$S_0$	$S_2$	$R_1$	$R_0$	$R_2$
$S_2$	$S_2$	$S_1$	$S_0$	$R_2$	$R_1$	$R_0$

The group  $D_4$ . This is the symmetry group of the square with vertices on the unit circle, at angles  $0, \pi/2, \pi$ , and  $3\pi/2$ . The matrix representation is given by

$$R_{0} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \qquad R_{1} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}, \qquad R_{2} = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}, \qquad R_{3} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix},$$
$$S_{0} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \qquad S_{1} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \qquad S_{2} = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}, \qquad S_{3} = \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix}.$$

while the Cayley table for  $D_4$  is:

	$R_0$	$R_1$	$R_2$	$R_3$	$S_0$	$S_1$	$S_2$	$S_3$
$R_0$	$R_0$	$R_1$	$R_2$	$R_3$	$S_0$	$S_1$	$S_2$	$S_3$
$R_1$	$R_1$	$R_2$	$R_3$	$R_0$	$S_1$	$S_2$	$S_3$	$S_0$
$R_2$	$R_2$	$R_3$	$R_0$	$R_1$	$S_2$	$S_3$	$S_0$	$S_1$
$R_3$	$R_3$	$R_0$	$R_1$	$R_2$	$S_3$	$S_0$	$S_1$	$S_2$
$S_0$	$S_0$	$S_3$	$S_2$	$S_1$	$R_0$	$R_3$	$R_2$	$R_1$
$S_1$	$S_1$	$S_0$	$S_3$	$S_2$	$R_1$	$R_0$	$R_3$	$R_2$
$S_2$	$S_2$	$S_1$	$S_0$	$S_3$	$R_2$	$R_1$	$R_0$	$R_3$
$S_3$	$S_3$	$S_2$	$S_1$	$S_0$	$R_3$	$R_2$	$R_1$	$R_0$